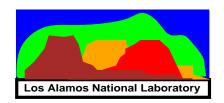


# ACCURATE TOP OF THE ATMOSPHERE ALBEDO DETERMINATION FROM MULTIPLE VIEWS OF THE MISR INSTRUMENT

Christoph C. Borel, Siegf<sub>ried</sub> A. W. Gerstl
MS C323, Los Alamos National Laboratory, Los Alamos, NM 87545, USA
Carmen Tornow

German Aerospace Research Establishment, Rudower Chaussee, 12484 Berlin

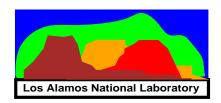
- Introduction
   Definition of TOA Albedo
- 2. Simulated MISR Data Set: JMRT Code
- 3. Azimuthal Models for the Top of the Atmosphere Reflectance: AZM, CSAR, Uniqueness, Noise Sensitivity
- 4. Clear Sky Top of Atmosphere Albedo Algorithm
- 5. Results: 4 Models
- 6 Conclusions



# Introduction

## Multi-angle Imaging Spectro-Radiometer (MISR):

- EOS-AM platform, launch in 1998
- ullet Nine cameras zenith angles of  $\pm 70.5$ ,  $\pm 60$ ,  $\pm 45$ ,  $\pm 26.1$  and 0 degrees in the along track direction
- Four spectral channels: 443 nm (blue), 550 nm (green), 670 nm (red) and 865 nm (near infrared)
- Misc: 275m pixels, 360 km swath, 9 day repeat
- Global Data Products: (georeferenced)
  - Top of the atmosphere spectral albedo (2.1km and 31km) (clear and cloudy conditions)
  - Surface hemispherical-directional reflectance factor (ocean: 2.1km and land: 1.1km),
  - Aerosol distributions (ocean: 2.2km and land: 17.6km).



# Definition of TOA Albedo

The albedo in each MISR channel  $c,\ c=[1,2,3,4]$  is defined according to Nicodemus et al, 1977, as:

$$\alpha_{0,c}(\mu_s) = \frac{1}{\pi} \int_0^1 d\mu_v \mu_v \int_0^{2\pi} d\phi_v \ BRF_c(\mu_s, \mu_v, \phi_v), \tag{1}$$

with the notation:

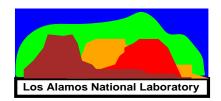
 $\alpha_{0,c}(\mu_s)$  is the top of atmosphere albedo in MISR channel c,

 $\phi_v$  is the angle relative to the solar azimuth,

 $\mu_s$  is the cosine of the solar zenith angle  $\theta_0$ ,

 $\mu_v$  is the cosine of the view zenith angle  $\theta$  and

 $BRF_c(\mu_s, \mu_v, \phi_v)$  is the bidirectional reflectance factor in MISR channel c.



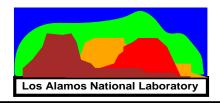
Relationship between the BRF and the bidirectional reflectance distribution function BRDF is:

$$BRDF_c(\mu_s, \mu_v, \phi_v) = \frac{1}{\pi} BRF_c(\mu_s, \mu_v, \phi_v). \tag{2}$$

The  $BRF_c$  is related to the radiance  $L_c$  by the following equation:

$$BRF_c(\mu_s, \mu_v, \phi_v) = \frac{\pi L_c(\mu_s, \mu_v, \phi_v) D^2}{\mu_s E_{0,c}},$$
 (3)

where  $D = R(t)/R_0$  is the normalized distance to the sun. R(t) is the time dependent distance and  $R_0$  is the distance for which  $E_0$  is defined and  $E_0$  is the TOA solar irradiance.



# Simulated MISR Data Set

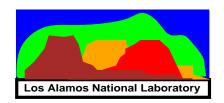
#### Motivation:

- No MISR data yet available
- Clear sky TOA albedo algorithm must be available at launch

### Requirements for simulated data set:

- "Radiative transfer" (RT) code must include BRDF
- Must calculate the multiple scattering for a large range of sun and view angles
- $\bullet$  Radiance with an error less than 1% requires an eight stream approximation (two stream approximations can cause up to 20% error)

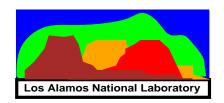
Two available codes: 6S (Vermote et al, 1994) and JMRT (Martonchik, 1994). (MODTRAN3 was not was not available prior to this work)



# "John Martonchik Radiative Transfer" (JMRT) Code

#### Features:

- Five different aerosol types (urban, rural, maritime, desert and arctic)
- 46 surface BRDF's from experimental data and models:
  - vegetation (23),
  - bare soil (3),
  - rough water surface (11),
  - snow and ice (9).
- Computes BRF in 10 zenith and 12 azimuthal angles
- Any additional surface BRDF's can be added
- Number of streams is variable



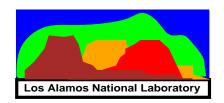
#### Albedo calculation:

• Simulated MISR data set uses 1-step Newton-Cotes integration:

$$\alpha_{0,c}(\mu_s) = Const \frac{2\pi}{N_{\phi} - 1} \sum_{i=1}^{N_{\theta} - 1} \mu_l \sum_{j=1}^{N_{\phi} - 1} \frac{\mu_i BRF_c(\mu_i, \phi_j) + \mu_{i+1} BRF_c(\mu_{i+1}, \phi_j)}{2(\mu_{i+1} - \mu_i)}, \quad (4)$$

where  $N_{\phi}=12$  is the number of azimuthal and  $N_{\theta}=10$  is the number of elevation angles, Const is determined by setting  $\alpha_0(\mu_s)=1$  with  $BRF_c(\mu_v,\phi_v)=1$  in eq.(4).

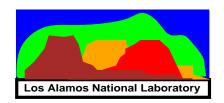
 $\bullet$  Inverted BRF model uses numerical integration with iterated Gaussian quadrature over  $\mu_v$  and  $\phi_v$ 



# Azimuthal Models for the TOA BRF

## Purpose and Requirements:

- MISR measures only in nine discrete directions ⇒ estimate the TOA radiance in directions which are not seen by MISR
- Azimuthal model (AZM) described BRF in other directions ⇒ semi-empirical function
  - As few parameters as possible,
  - Uniquely invertible
  - Reciprocal (sun and view angles are interchangeable without changing the value)
  - Little sensitivity to noise.



# Coupled Surface-Atmosphere Reflectance (CSAR)

$$BRF_{CSAR}(\theta_s, \phi_s; \theta_v, \phi_v) = \varrho_0 \frac{\mu_s^{\kappa-1} \mu_v^{\kappa-1}}{(\mu_s + \mu_v)^{1-\kappa}} F(g)[1 + R(G)],$$
 (5)

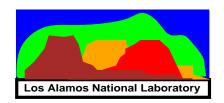
where  $\varrho_0$  and  $\kappa$  are empirical surface parameters between 0 and 1 with the condition on  $\varrho_0$  that the albedo of eq.(5) is between 0 and 1, and F(g) is the Henyey-Greenstein function:

$$F(g) = \frac{1 - \Theta_0^2}{[1 + \Theta_0^2 - 2\Theta_0 \cos(\pi - g)]^{1.5}}$$

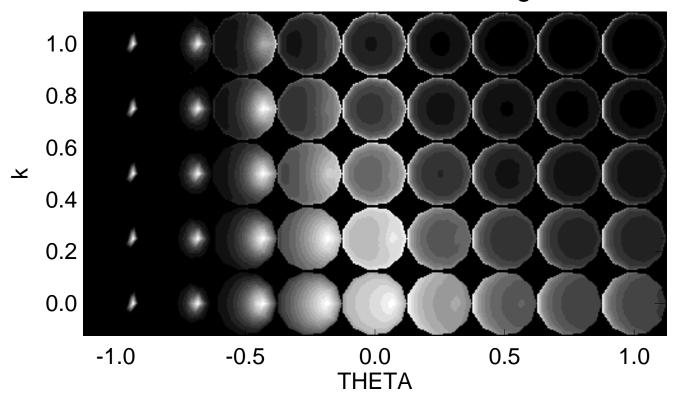
 $\Theta_0$  controls the forward  $(0 \le \Theta_0 \le 1)$  and backward (hot spot)  $(-1 \le \Theta_0 \le 0)$  scattering peak, g is a phase angle and given by:  $\cos g = \mu_s \mu_v + \sin \theta_s \sin \theta_v \cos(\phi_s - \phi_v)$ , (1 + R(G)) approximates the hot-spot with:

$$1 + R(G) = 1 + \frac{1 - \varrho_0}{1 + G},$$

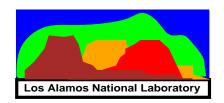
where  $G = \sqrt{\tan^2 \theta_s + \tan^2 \theta_v - 2 \tan \theta_s \tan \theta_v \cos(\phi_s - \phi_v)}$ .



# Normalized Rahman BRDF: Sun Zenith=32.5000 deg



Polar representation of the CSAR BRF for  $\theta_s=32.5^o$  and  $\varrho_0=0.2$  as a function of  $\Theta_0$  and  $\kappa$ .



# Uniqueness

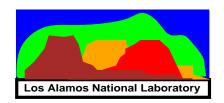
#### **Problem:**

Given a BRF slice for a given CSAR parameter set  $(\varrho_0, \kappa \text{ and } \Theta_0)$  can we recover the original parameter set using non-linear least square fitting?

#### **Procedure:**

- 1. Generate  $N_p$  randomly chosen parameters:  $\varrho_{0,i}, \ \kappa$  and  $\Theta_{0,i}, \ i=1,2,3,\ldots,N_p$ .
- 2. Calculate  $N_p$  BRF slices  $BRF(\theta_s, \phi_s; \vec{\theta_v}, \vec{\phi_v}; \varrho_{0,i}, \kappa, \Theta_{0,i})$  using eq.(5).
- 3. Invert BRF model for  $\widehat{\varrho_{0,i}}$ ,  $\widehat{\kappa}$  and  $\widehat{\Theta_{0,i}}$ .
- 4. Compute errors  $\varepsilon(\varrho_{0,i}) = \widehat{\varrho_{0,i}} \varrho_{0,i}$ ,  $\varepsilon(\kappa) = \widehat{\kappa} \kappa$  and  $\varepsilon(\Theta_{0,i}) = \widehat{\Theta_{0,i}} \Theta_{0,i}$  and the "Root Mean Square Error" (RMSE) of the BRF slice difference  $(B\widehat{R}F_i BRF_i)$ .

Result: Yes, the CSAR model appears unique



# **Noise Sensitivity**

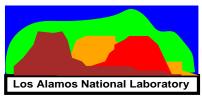
#### **Problems:**

(A) How much noise can be tolerated in the inversion? (B) How does the albedo error change as a function of added noise?

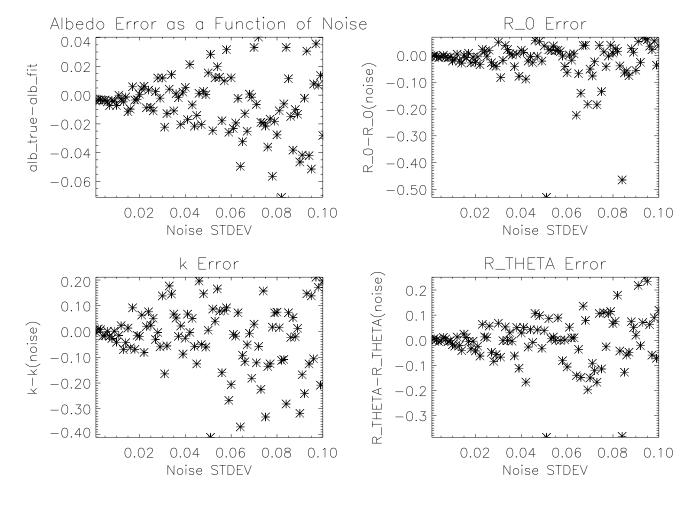
#### **Procedure:**

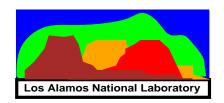
- 1. Generate a BRF slice BRF for a fixed set of parameters:  $\theta_s = 30^o$ ,  $\varrho_0 = 0.5$ ,  $\kappa = 0.3$  and  $\Theta_0 = 0.22$  and compute the albedo  $\alpha_0$  using a numerical integration technique (e.g. 1-step or 5-step Newton-Cotes integration).
- 2. For  $i = 1, \ldots, N_p$  cases do:
  - (a)  $BRF_i = BRF + \sigma_i N_i(0,1)$ , where  $N(0,\sigma_i)$  denotes the i-th realization of a Gaussian distributed random vector with mean 0 and standard deviation  $\sigma_i$  where  $\sigma_i = \{1,2,3,\ldots,N_p\}\Delta_{\sigma}$  and  $\Delta_{\sigma}$  is an increment.
  - (b) Retrieve the BRF parameters:  $\widehat{\varrho_{0,i}}$ ,  $\widehat{\kappa}$  and  $\widehat{\Theta_{0,i}}$  and the fitted  $\widehat{BRF_i}$ . Compute the albedo  $\widehat{\alpha_0}$  of the inverted BRF.
- 3. Plot the BRF,  $BRF_i$  and  $B\widehat{R}F_i$  as a function of MISR camera angle.
- 4. Plot  $\sigma_i$  on the x-axis and  $[(\alpha_0 \widehat{\alpha_{0,i}}), (BRF B\widehat{R}F_i), (\varrho_0 \widehat{\varrho_{0,i}}), (\kappa \widehat{\kappa}), (\Theta_0 \widehat{\Theta_{0,i}})]$  on the y-axis.





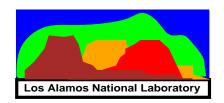
Results: (A) The error between original and retrieved BRF parameters grows linearly with increased noise. (B) The albedo error was less than  $\pm 5\%$  for  $\sigma \leq 0.1$  for an albedo of 0.43.





# Clear Sky Top of Atmosphere Albedo Algorithm

- 1. Read TOA BRFs from JMRT output.
- 2. For all  $N_k$  cases  $k = 1, 2, 3, ..., N_k$  do:
  - (a) Compute the albedo  $\alpha_{0,k}$  using Newton-Cotes integration over the quadrature angles.
  - (b) For view azimuthal angles  $\phi_j = [0^o, 30^o, 60^o, 90^o]$  do:
    - i. Extract a BRF slice  $(BRF_i, i = 1, 2, ..., 9)$  at the MISR angles for  $(\phi_j, \phi_j + 180^o)$ .
    - ii. Perform nonlinear curve fit of  $BRF_{j,i}$  results in estimated CSAR parameters  $\widehat{\varrho_{0,j,k}}$ ,  $\widehat{\kappa_{j,k}}$  and  $\widehat{\Theta_{0,j,k}}$ .
    - iii. Do a numerical integration of CSAR model over the hemisphere results in estimated albedo  $\widehat{\alpha_{0,j,k}}$ .
    - iv. Compute albedo error  $\varepsilon(\alpha_{0,j,k}) = \alpha_{0,k} \widehat{\alpha_{0,j,k}}$ .
  - (c) Plot standard deviation  $\sigma$  of the albedo error  $\varepsilon(\alpha_{0,j,k}(\phi_j))$
  - (d) Generate TOA BRF from estimated CSAR parameters and display.
- 3. Generate scatter plots of standard deviation of the albedo error versus azimuth marking different surface types with symbols.



# Results

#### **Error Metric:**

Standard deviation  $\sigma$  of the albedo error

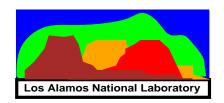
#### Cases:

- 5 different atmospheres
- 3 sun angles  $(15^o, 32.5^o, 50^o)$
- 4 different azimuthal angles at  $(0^o, 30^o, 60^o \text{ and } 90^o)$

#### $\Rightarrow$ 2760 cases

Computing time:  $\approx$  1h on Sparc 10 (includes visualization)

Note: Faster inversion routines must be found to make this approach practicable for the EOS data information system



# Three Parameters (no Limits) CSAR Model

Motivation: Easy to perform nonlinear least squares curve fit without bounded parameters

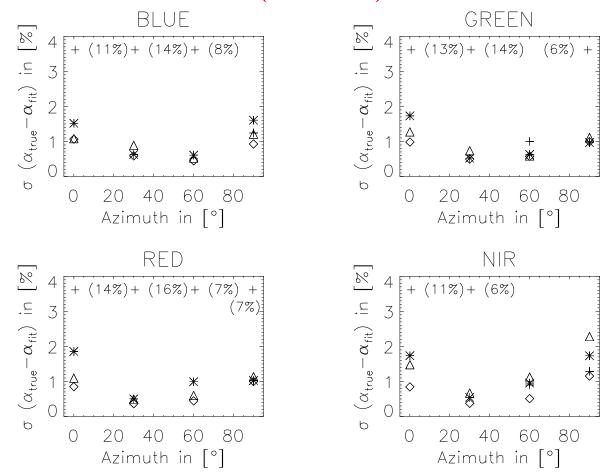
$$BRF_1(\theta_i, \phi_i) = BRF_{CSAR}(\theta_i, \phi_i; \varrho_0, \kappa, \Theta_0), i = 1, \dots, 9$$
(6)

Result: For snow and ice which have larger reflectances and a more Lambertian character, the errors exceeded the 5% level for many azimuthal angles.

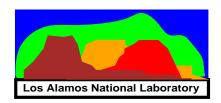
Reason: The inversion routine which was not able to find a good solution in the 20 iteration limit and RMSE error limits of 0.001.



### Three Parameters (no Limits) CSAR Model



Symbols used:  $\triangle$  Vegetation (23 models),  $\diamond$  Soil and sand (3 models), + Snow and ice (9 models) and \* Water (11 models). Note: plot data points outside the 4% limit as symbols with an error in % in brackets.



# Two Parameters (with Limits) CSAR Model

Motivation: MISR does not measure in the principle plane  $\Rightarrow$  do not use parameter which models forward or backward scattering

$$BRF_2(\theta_i, \phi_i) = BRF_{CSAR}(\theta_i, \phi_i; \varrho_0', \kappa', F(g) = 1), \quad i = 1, \dots, 9.$$
(7)

Variable transform: from the original unbound variable  $\varrho_0$  to the interval limited variable  $\varrho'_0$  was used:

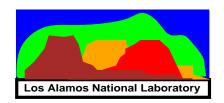
$$\varrho_0' = \frac{1}{2} + \frac{\tan^{-1}(\varrho_0)}{\pi}$$

and it's inverse:

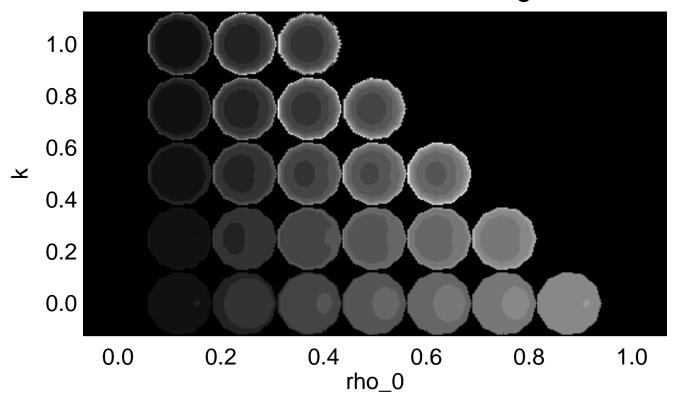
$$\varrho_0 = \tan(\pi(\varrho_0 - \frac{1}{2})).$$

Similarilly  $\kappa$  can be transformed to  $\kappa'$ .

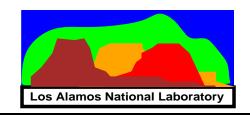
Result: The method works well for all cases and channels ( $\sigma < 3.8\%$ ) For more typical MISR azimuthal angles between  $30^o$  and  $60^o$  the albedo errors are below 2% which is very good.



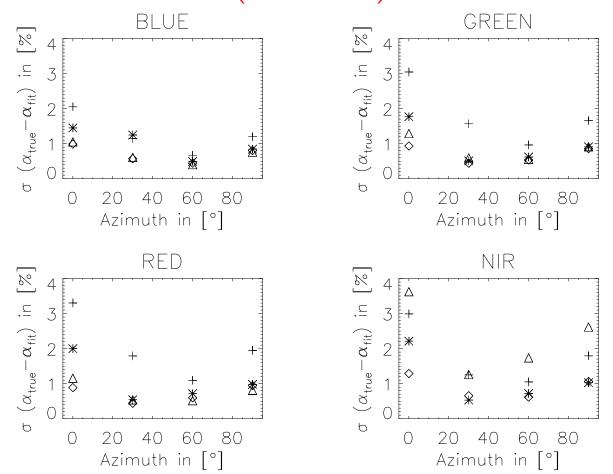
Two Parameter BRDF: Sun Zenith=32.5000 deg



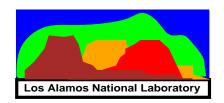
Polar representation of the two parameter CSAR BRF for  $\theta_s=32.5^o$  as a function of  $\varrho_0$  and  $\kappa$ .



## Two Parameters (with Limits) CSAR Model



Symbols used:  $\triangle$  Vegetation (23 models),  $\diamond$  Soil and sand (3 models), + Snow and ice (9 models) and \* Water (11 models).



# **Atmospheric Transmission Correction**

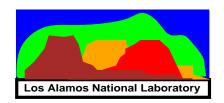
Motivation: Visualizing the resulting TOA BRF fields for the  $BRF_1$  and  $BRF_2$  models we noticed that the BRF near the horizon ( $80^o < \theta_v < 90^o$ ) often was very much larger than the computed BRF from JMRT.

Idea: Include atmospheric terms, e.g. transmission.

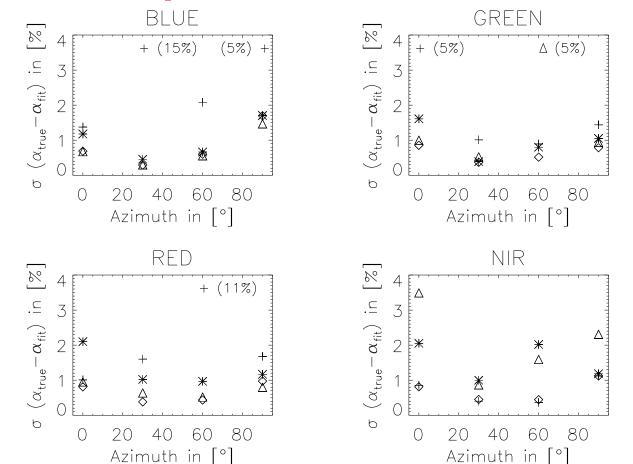
$$BRF_3(\theta_i, \phi_i) = BRF_{CSAR}(\theta_i, \phi_i; \varrho_0, \kappa, \Theta) \exp(-\tau_c/\mu_i), \quad i = 1, \dots, 9; \quad c = 1, 2, 3, 4$$
 (8)

where the mean transmission factor  $T_c = \exp(-\tau_c/\mu_i)$  and  $\tau_c = [.24, .094, .043, .015]$  and c is the channel indicator.

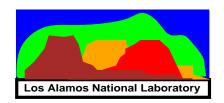
Result: Works well for blue channel and in the principle plane  $\phi = 0^o$ . Converges for all cases for the NIR to less than 3.8%  $\sigma$ .



## **Atmospheric Transmission Correction**



Symbols used:  $\triangle$  Vegetation (23 models),  $\diamond$  Soil and sand (3 models), + Snow and ice (9 models) and \* Water (11 models).



# **Atmospheric Pre-Correction**

Motivation: Visualizing the resulting TOA BRF fields for the  $BRF_1$  and  $BRF_2$  models we noticed that the BRF near the horizon ( $80^o < \theta_v < 90^o$ ) often was very much larger than the computed BRF from JMRT.

Idea: Include atmospheric terms, e.g. transmission and path radiance from Rayleigh scattering.

$$BRF_4(\theta_i, \phi_i) = BRF_{CSAR}(\theta_i, \phi_i; \varrho_0, \kappa, \Theta_0) \exp(-\tau_c/\mu_i) - BRF_{Rayleigh}(\theta_i, \phi_i)$$

$$, i = 1, 2, 3, \dots, 9; c = 1, 2, 3, 4$$

$$(9)$$

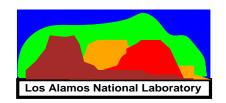
and the albedo is given by the sum of:

$$\alpha_0 = Albedo(BRF_{CSAR,fit}(\theta_i, \phi_j) \exp(-\tau_c/\mu_i)) + Albedo(BRF_{Rayleigh}(\theta_i, \phi_j)),$$

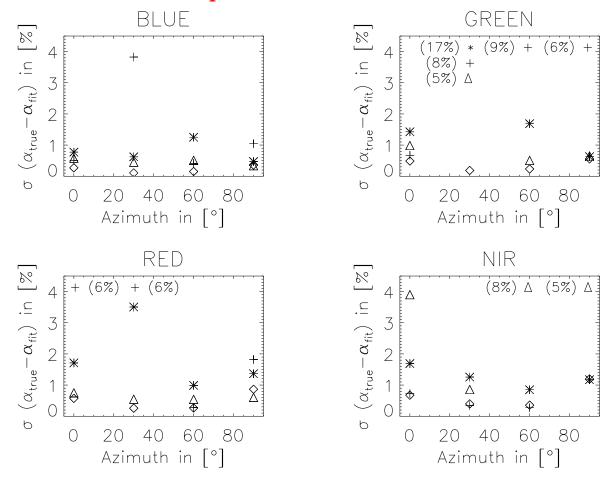
$$i = 1, 2, 3, \dots, N_{\theta}; \ j = 1, 2, 3, \dots, N_{\phi}; \ c = 1, 2, 3, 4,$$
 (10)

where  $BRF_{CSAR,fit}(\theta_i,\phi_j)$  is the hemispherical BRF computed from the best fit of the CSAR parameters to the BRF slice  $BRF_4(\theta_i,\phi_i)$ .

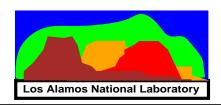
Result: Works well for blue channel and in the principle plane  $\phi=0^o$ . Convergence problems, probably because no limits on the CSAR parameters is used.



## **Atmospheric Pre-Correction**



Symbols used:  $\triangle$  Vegetation (23 models),  $\diamond$  Soil and sand (3 models), + Snow and ice (9 models) and \* Water (11 models).

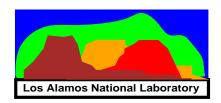


# Conclusions

- Albedo error is less than 1% in the visible and less than 1.5% in the NIR If only nadir measurements are used the albedo error is about 5 % in the visible and 10 % in the NIR.
- More work needed to make this approach robustly work for all surfaces and atmospheric conditions.
- Need to perform the inversion more rapidly and flag pixels for which the model did not fit very well.
- This approach lends itself to calculate the hemispherical BRF field over any region of the Earth.

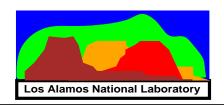
# Future Work

- Investigate other semi-empirical BRF models.
- How the BRF-CSAR parameters vary as a function of sun angle?
- Is there a diurnal smooth trajectory for a parameter with sun angle? If so, we could use this to predict the TOA clear sky albedo at times of the day.



# Acknowledgments

This work was supported by the Multi-angle Imaging Spectro Radiometer (MISR) project through a contract from NASA/JPL. We recognize the significant contributions by Dr. Veronique Carrére (JRC, Ispra) and Heather Stephens (LANL) and Kerstin Lippert (LANL and DLR, Berlin).



# References

Diner D.J., Clothiaux E., Conel J.E., Davies R., Di Girolamo L., Muller J.-P., Varnai T. and Wenkert D., 1994, MISR Level 2 Algorithm Theoretical Product: TOA/Cloud Product, JPL Report D-11399, March 3.

Nicodemus F.E., Richmond J.C., Hsia J.J., Ginsberg I.W. and Limperis T., 1977, Geometrical Considerations and Nomenclature for Reflectance, Washington, D.C.: NBS Monograph 160, National Bureau of Standards, Dept. of Commerce, p.52.

Rahman H., Verstraete M.M. and Pinty B., 1993, Coupled Surface-Atmosphere Reflectance (CSAR) Model (parts 1 and 2), JGR, 98:D11:20,779-20,789 and 98:D11:20,791-20,801.

Vermote E., Tanré D., Deuzé J.L., Herman M. and Morcette J.J., 1994, Second Simulation of the Satellite Signal in the Solar Spectrum, 6S User Guide Version n, NASA-Goddard Space Flight Center, Greenbelt, USA, p. 182.